

## Jülich Institute – Fieldship UAV blimp

Peter Lobner, 19 June 2023

The 10-meter (32.8-ft) Fieldship unmanned aerial vehicle (UAV) blimp operated by the Jülich Institute was acquired in 2013 to serve as a remote sensing platform for a variety of studies, many led by the



Institute of Bio- and Geosciences (IBG-2) and dealing with plant sciences. The Fieldship is stored and operated at the Campus Klein-Altendorf near to Bonn.

The Fieldship blimp enables surveillance of agricultural areas for long periods of time. The smooth flight characteristics with low vibrations make the UAV blimp a good platform for carrying remote sensing instrumentation packages that complement the remote sensing capabilities of other types of small UAV platforms used by Jülich Institute (i.e., quad-copters).



*Jülich Fieldship UAV blimp in low-level flight.  
Source: Jülich Institute*

Since its acquisition, the Fieldship has been significantly improved with the addition of an autopilot to enable semi-autonomous operations.

### General characteristics of the Jülich Fieldship UAV blimp

| Parameter        | Fieldship UAV blimp   |
|------------------|---|
| Type             | Non-rigid, pressure stabilized hull   |
| Length           | 10 meters (32.8 ft)   |
| Diameter, max    | About 3.2 meters (10.0 ft)  |
| Lifting gas      | Helium  |
| Volume           | 24m <sup>3</sup> (848 ft <sup>3</sup> )   |
| Payload capacity | 5 kg (11 lb)  |
| Power source     | Batteries   |
| Propulsion       | Two x 1 kW (1.4 hp) brushless electric motor driven propellers, cantilevered from the small gondola |
| Endurance        | 60 minutes  |



*Jülich Fieldship UAV blimp. Source: Jülich Institute*



*Agricultural areas and specific experiments recorded using the UAV blimp platform at multiple times during the 2017 growing season. Source: Jülich Institute*

### **For more information**

- “Field investigations from the air with unmanned aerial vehicles (UAV's),” Jülich Institute, 2017: [https://www.fz-juelich.de/ibg/ibg-2/EN/Research/ResearchGroups/shoot\\_dynamics/technologies/UAV/UAV\\_node.html](https://www.fz-juelich.de/ibg/ibg-2/EN/Research/ResearchGroups/shoot_dynamics/technologies/UAV/UAV_node.html)

- “Analysis of fields from the top with unmanned air vehicles (UAV's),” Jülich Institute: [https://www.fz-juelich.de/ibg/ibg-2/EN/methods\\_jppc/UAV\\_ZeppOcto/\\_node.html](https://www.fz-juelich.de/ibg/ibg-2/EN/methods_jppc/UAV_ZeppOcto/_node.html)
- F. Fiorani, et al., “Opportunities and challenges for the development of a European plant phenotyping research infrastructure,” Jülich Institute, Institute of Bio- and Geosciences (IBG-2), Jülich Plant Phenotyping Center, 2016: <http://www.trees4future.eu/uploads/Final%20conference/Presentations/Session1/2%20-%20Fiorani.pdf>

### **Other *Modern Airships* articles**

- *Modern Airships - Part 1*: <https://lynceans.org/all-posts/modern-airships-part-1/>
- *Modern Airships - Part 2*: <https://lynceans.org/all-posts/modern-airships-part-2/>
- *Modern Airships - Part 3*: <https://lynceans.org/all-posts/modern-airships-part-3/>